# Consistent Accelerated Inference via Confident Adaptive Transformers

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#### Overview

**Goal**: Reduce the computational effort of multilayered deep models while ensuring consistency with the original model  $\mathcal{F}$  that uses l layers.

**Approach**: A new model  $\mathcal{G}$  that can exit at layer  $\leq l$  and guarantees:

$$\mathbb{P}\big(\mathcal{G}(X_{n+1}) = \mathcal{F}(X_{n+1})\big) \ge 1 - \epsilon$$

Specifically, our model is defined as:

$$\mathcal{G}(x; \boldsymbol{\tau}) := \begin{cases} \mathcal{F}_1(x) & \text{if } \mathcal{M}_1(x) > \tau_1, \\ \mathcal{F}_2(x) & \text{else if } \mathcal{M}_2(x) > \tau_2, \\ \vdots & \vdots \\ \mathcal{F}_l(x) & \text{otherwise,} \end{cases}$$

Where  ${\cal M}$  are confidence scores and  $\tau$  are stopping thresholds.

### **Challenges:**

- 1) What is a good confidence score? Meta predictor
- 2) How to calibrate the thresholds? Conformal calibration over inconsistent layers

## **Conformalized Early Exit**

We look at **inconsistent** layers:

$$\mathcal{I}(x):=\{i:\mathcal{F}_i(x)
eq\mathcal{F}(x)\}\,,\quad i\in[1,l-1]$$
 and obtain a conservative prediction set  $\mathcal{C}_\epsilon$  s.t.:

$$\mathbb{P}\left(\mathcal{I}\left(X_{n+1}\right)\subseteq\mathcal{C}_{\epsilon}\left(X_{n+1}\right)\right)\geq1-\epsilon$$

The first layer in the complement set provides:

$$\mathbb{P}\left(\mathcal{F}_{K}\left(X_{n+1}\right) = \mathcal{F}\left(X_{n+1}\right)\right) \geq 1 - \epsilon,$$

$$K := \min\left\{i : i \in C^{c}\left(X_{n+1}\right)\right\}$$

where  $K := \min \{j : j \in \mathcal{C}^{c}_{\epsilon}(X_{n+1})\}$ .

**Independent calibration**: For each layer, compute the empirical distribution over a calibration set:

$$v_k^{(1:n,\infty)} := \left\{ \mathcal{M}_k\left(x_i\right) : x_i \in \mathcal{D}_{\text{cal}}, \mathcal{F}_k\left(x_i\right) \neq \mathcal{F}\left(x_i\right) \right\} \cup \left\{\infty\right\}.$$

Take the quantile after MHT correction:

$$\tau_k^{\text{ind}} = \text{Quantile}(1 - \alpha_k, v_k^{(1:n,\infty)})$$

**Shared Calibration**: Calibrate for the *worst-case* across inconsistent layers (the maximum score):

$$m^{(1:n,\infty)} := \{ \mathcal{M}_{\max}(x_i) : x_i \in \mathcal{D}_{\operatorname{cal}}, \exists k \mathcal{F}_k(x_i) \neq \mathcal{F}(x_i) \} \cup \{\infty\};$$

$$\tau^{\operatorname{share}} = \operatorname{Quantile} \left( 1 - \epsilon, m^{(1:n,\infty)} \right)$$

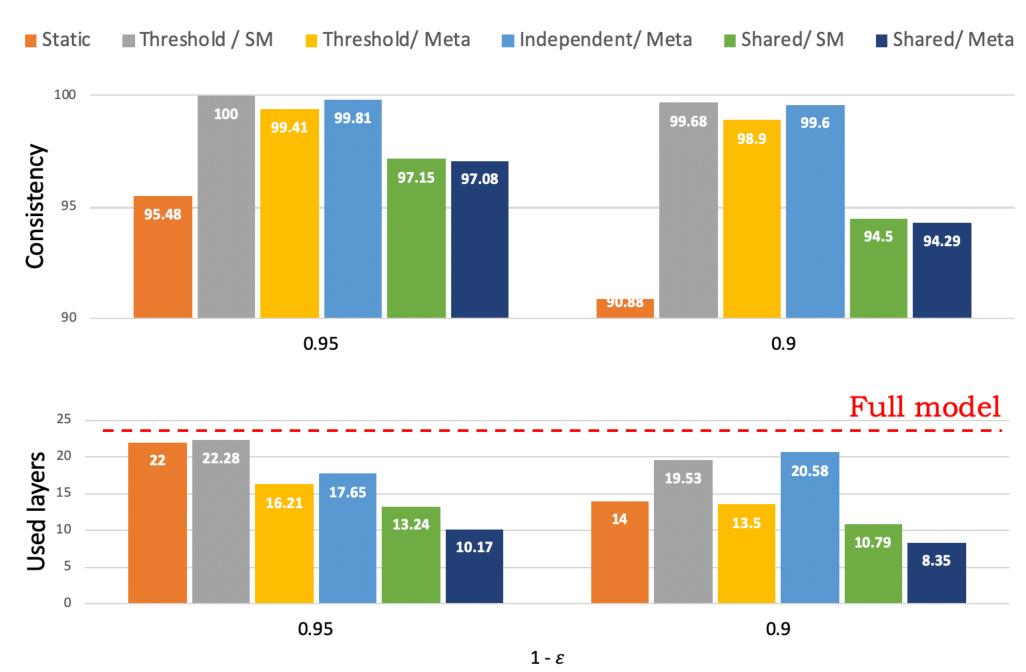
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## **Experiments**

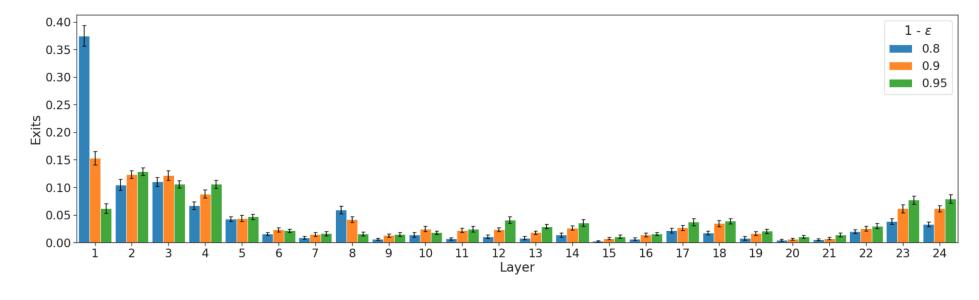
**Experimental setting**: we implement our **C**onfident **A**daptive **T**ransformers (CATs) on top of popular models (e.g. Albert). We evaluate on four NLP tasks covering both classification and regression.

Evaluated on IMDB, VitaminC, AG news, STS-B

#### **Results** on AG news:



The distribution of exit layers is dynamically controlled by the user-defined tolerance level:



Amortized time  $(1 - \epsilon = 0.9)$ :

